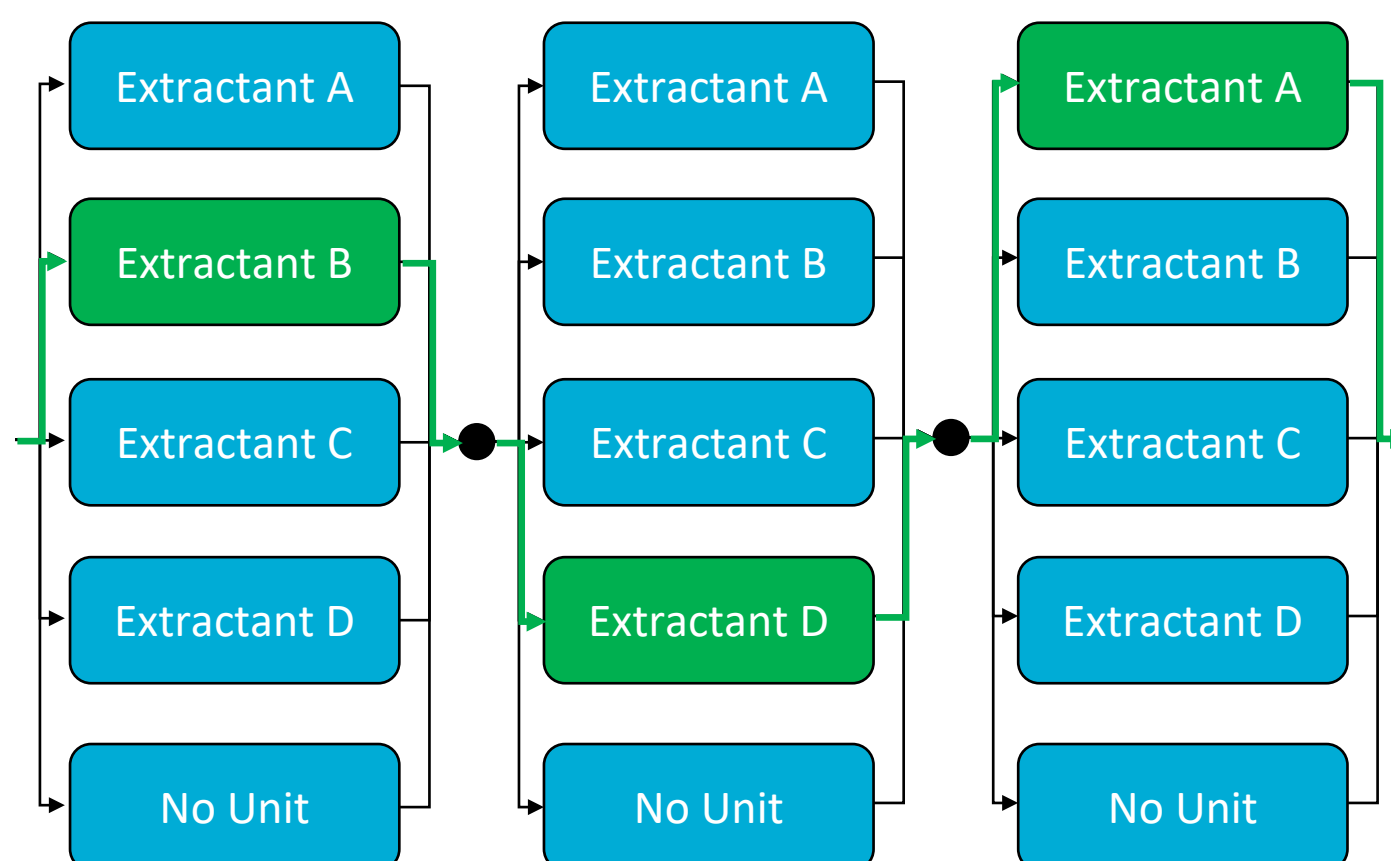




What is Generalized Disjunctive Programming (GDP)?

- Modeling framework for expressing discrete decisions and logical constraints (e.g., Solvent extraction sequencing)
- Naturally supports nested decisions, for example:

$$\begin{aligned} \max \quad & x \\ \text{s.t.} \quad & \left[\begin{array}{c} Y_1 \\ 1.15 \leq x \leq 8 \\ Z_1 \end{array} \right] \vee \left[\begin{array}{c} Z_2 \\ x \geq 1.1 \\ Z_1 \vee Z_2 \end{array} \right] \vee \left[\begin{array}{c} Y_2 \\ x = 9 \end{array} \right] \\ & Y_1 \vee Y_2 \\ & Y_2 \implies Z_1 \wedge Z_2 \\ & 1 \leq x \leq 10 \end{aligned}$$



- Enables systematic design for complex processes (CM processing)

GDP Provides Solution Flexibility

- GDPs can be solved directly with specialized algorithms: via outer approximation, logic-based branch and bound, or, for few enough disjunctions, enumeration.
- Alternatively, there are myriad transformations from GDP to MINLP in the literature, most of which are implemented in Pyomo^[1,2].



| Transformation | Advantages | Disadvantages |
|-----------------------|---|---|
| Big-M | Simple, requires few variables/constraints, familiar structure for solvers | Potentially weak continuous relaxation |
| Hull | Tighter continuous relaxation | Large model: Requires many variables/constraints |
| Multiple Big-M | Tighter continuous relaxation with smaller model | Requires calculating quadratically many M values |
| Binary Multiplication | Additional structure for solver to exploit | Introduces nonlinearity |
| Between Steps | Tighter continuous relaxation with smaller model in cases where there are many more variables than constraints in each disjunct | Relaxation quality is sensitive to choice of variable partition and variable bounds |
| Cutting planes | Targeted tightening of Big-M relaxation in direction of improved objective values | Can cause numerical instability |

Theory vs. Practice

The Question: What solution techniques are best for what problems?

- For linear GDPs, we know from experience that theoretically good formulations (e.g., hull) are rarely good in practice using commercial solvers (e.g. Gurobi) and are in fact outperformed by Big-M usually.
- Given advances in MIQCP and MINLP solvers, binary multiplication may be becoming tractable
- We have limited computational experience with hybrid formulations between Big-M and hull: What structures are amenable for these?

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Preliminary Computational Results

Experimental setup:

- Baron Version 24.1.5
- Time limit of 500 seconds (denoted by 'T')
- Solved NLP relaxation with ipopt. 'NC' denotes that it did not converge.
- Every GDP-to-MINLP transformation in pyomo.gdp
- Two transformation of logical constraints: a sparse one using factorable programming (FP), and one to conjunctive normal form (CNF)

GDP Reactor (CSTR) Model^[3]

| Logical Transformation | GDP-to-MINLP Transformation | Baron Solve Time (s) | Nodes Explored | LB | UB | NLP Relaxation | LB After Presolve | UB After Presolve |
|------------------------|-----------------------------|----------------------|----------------|------|------|----------------|-------------------|-------------------|
| FP | Big-M | 16 | 6297 | 3.06 | 3.06 | 0.00 | 0.09 | 3.06 |
| FP | Hull | 51 | 21461 | 3.06 | 3.06 | 0.00 | 0.09 | 3.13 |
| FP | Cutting planes | T | 330747 | 2.91 | 3.06 | 0.00 | 0.09 | 3.06 |
| FP | Multiple Big-M | NA | | | | | | |
| FP | Binary Multiplication | 111 | 11516 | 3.06 | 3.06 | NC | 0.09 | 3.06 |
| FP | Between Steps: p=2 | 136 | 4189 | 3.06 | 3.06 | 0.00 | 0.05 | 4.06 |
| FP | Between Steps: p=3 | T | 140371 | 2.92 | 3.06 | 0.00 | 0.05 | 4.06 |
| FP | Between Steps: p=4 | 137 | 7558 | 3.06 | 3.06 | 0.00 | 0.05 | 9.89 |
| CNF | Big-M | 11 | 4675 | 3.06 | 3.06 | 0.00 | 0.09 | 3.06 |
| CNF | Hull | T | 538389 | 3.04 | 3.06 | 0.00 | 0.09 | 3.06 |
| CNF | Cutting planes | T | 1249456 | 3.02 | 3.06 | 0.00 | 0.09 | 3.06 |
| CNF | Multiple Big-M | T | 1110055 | 2.91 | 3.06 | 0.00 | 0.09 | 3.06 |
| CNF | Binary Multiplication | T | 301025 | 3.00 | 3.06 | NC | 0.09 | 3.06 |
| CNF | Between Steps: p=2 | 131 | 4189 | 3.06 | 3.06 | 0.00 | 0.05 | 4.06 |
| CNF | Between Steps: p=3 | T | 141129 | 2.92 | 3.06 | 0.00 | 0.05 | 4.06 |
| CNF | Between Steps: p=4 | 138 | 7558 | 3.06 | 3.06 | 0.00 | 0.05 | 9.89 |

Batch Processing Model^[4]

| GDP-to-MINLP Transformation | Baron Solve Time (s) | Nodes Explored | Lower Bound | Upper Bound | NLP Relaxation | LB After Presolve | UB After Presolve |
|-----------------------------|----------------------|----------------|-------------|-------------|----------------|-------------------|-------------------|
| Big-M | T | 79 | 607575 | 684827 | 546850 | 579099 | 712688 |
| Hull | T | 27 | 612034 | 684455 | 547333 | 577482 | 12206917 |
| Cutting planes | 426 | 563 | 679365 | 679365 | 546850 | 668226 | 680249 |
| Multiple Big-M | T | 168 | 670523 | 680249 | 547333 | 574856 | 680249 |
| Binary Multiplication | T | 5 | 592717 | 680249 | 715226 | 592717 | 694108 |
| Between Steps: p=2 | T | 7 | 574481 | 702026 | 546850 | 574481 | 714243 |
| Between Steps: p=3 | T | 4 | 581970 | 694605 | 546850 | 581970 | 694605 |
| Between Steps: p=4 | T | 6 | 585961 | 680249 | 546850 | 571656 | 680249 |

Conclusions:

- There is no conclusion: That's why we have a toolbox!
- It is model-dependent what technique will result in the shortest solve time, and in some cases, even in a tractable model.
- While there is correlation between faster solve time and fewer nodes explored in the tree, some formulations explore many more nodes faster and can still be superior if solve time is the metric of success.
- Even when it is the preferable transformation, cutting planes does not always improve the relaxation from the Big-M transformation!

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